THE CHEMIST'S TOOLKIT 25 Matrix methods for solving eigenvalue equations

In matrix form, an eigenvalue equation is

where *M* is a square matrix with *n* rows and *n* columns, λ is a constant, the **eigenvalue**, and *x* is the **eigenvector**, an $n \times 1$ (column) matrix that satisfies the conditions of the eigenvalue equation and has the form:

$$\boldsymbol{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

 $Mx = \lambda x$

In general, there are *n* eigenvalues $\lambda^{(i)}$, i = 1, 2, ..., n, and *n* corresponding eigenvectors $\mathbf{x}^{(i)}$. Equation 25.1a can be rewritten as

$$(M - \lambda 1)x = 0 \tag{25.1b}$$

where 1 is an $n \times n$ unit matrix, and where the property $\mathbf{1}x = x$ has been used. This equation has a solution only if the determinant $|M - \lambda 1|$ of the matrix $M - \lambda 1$ is zero. It follows that the *n* eigenvalues may be found from the solution of the **secular equation**:

$$|M - \lambda 1| = 0 \tag{25.2}$$

Brief illustration 25.1: Simultaneous equations

Consider the matrix equation

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \lambda \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

rearranged into $\begin{pmatrix} 1 - \lambda & 2 \\ 3 & 4 - \lambda \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$

From the rules of matrix multiplication, the latter form expands into

$$\begin{pmatrix} (1-\lambda)x_1+2x_2\\ 3x_1+(4-\lambda)x_2 \end{pmatrix} = 0$$

which is simply a statement of the two simultaneous equations

$$(1-\lambda)x_1+2x_2=0$$
 and $3x_1+(4-\lambda)x_2=0$

The condition for these two equations to have solutions is

$$|\mathbf{M} - \lambda \mathbf{l}| = \begin{vmatrix} 1 - \lambda & 2 \\ 3 & 4 - \lambda \end{vmatrix} = (1 - \lambda)(4 - \lambda) - 6 = 0$$

This condition corresponds to the quadratic equation

$$\lambda^2 - 5\lambda - 2 = 0$$

with solutions $\lambda = +5.372$ and $\lambda = -0.372$, the two eigenvalues of the original equation.

The *n* eigenvalues found by solving the secular equations are used to find the corresponding eigenvectors. To do so, begin by considering an $n \times n$ matrix *X* the columns of which are formed from the eigenvectors corresponding to all the eigenvalues. Thus, if the eigenvalues are $\lambda_1, \lambda_2, ...,$ and the corresponding eigenvectors are

$$\boldsymbol{x}^{(1)} = \begin{pmatrix} x_1^{(1)} \\ x_2^{(1)} \\ \vdots \\ x_n^{(1)} \end{pmatrix} \quad \boldsymbol{x}^{(2)} = \begin{pmatrix} x_1^{(2)} \\ x_2^{(2)} \\ \vdots \\ x_n^{(2)} \end{pmatrix} \quad \cdots \quad \boldsymbol{x}^{(n)} = \begin{pmatrix} x_1^{(n)} \\ x_2^{(n)} \\ \vdots \\ x_n^{(n)} \end{pmatrix}$$
(25.3a)

then the matrix X is

$$X = (\mathbf{x}^{(1)} \ \mathbf{x}^{(2)} \cdots \mathbf{x}^{(n)}) = \begin{pmatrix} x_1^{(1)} & x_1^{(2)} & \cdots & x_1^{(n)} \\ x_2^{(1)} & x_2^{(2)} & \cdots & x_2^{(n)} \\ \vdots & \vdots & & \vdots \\ x_n^{(1)} & x_n^{(2)} & \cdots & x_n^{(n)} \end{pmatrix}$$
(25.3b)

Similarly, form an $n \times n$ matrix Λ with the eigenvalues λ along the diagonal and zeroes elsewhere:

$$\boldsymbol{\Lambda} = \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{pmatrix}$$
(25.4)

Now all the eigenvalue equations $Mx^{(i)} = \lambda_i x^{(i)}$ may be combined into the single matrix equation

$$MX = X\Lambda \tag{25.5}$$

Brief illustration 25.2: Eigenvalue equations

In Brief illustration 25.1 it is established that if
$$M = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$$

then $\lambda_1 = +5.372$ and $\lambda_2 = -0.372$. Then, with eigenvectors
 $\mathbf{x}^{(1)} = \begin{pmatrix} x_1^{(1)} \\ x_2^{(1)} \end{pmatrix}$ and $\mathbf{x}^{(2)} = \begin{pmatrix} x_1^{(2)} \\ x_2^{(2)} \end{pmatrix}$ form
 $\mathbf{X} = \begin{pmatrix} x_1^{(1)} & x_1^{(2)} \\ x_2^{(1)} & x_2^{(2)} \end{pmatrix} \mathbf{A} = \begin{pmatrix} 5.372 & 0 \\ 0 & -0.372 \end{pmatrix}$

The expression
$$MX = X\Lambda$$
 becomes

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} x_1^{(1)} & x_1^{(2100)} \\ x_2^{(1)} & x_2^{(2)} \end{pmatrix} = \begin{pmatrix} x_1^{(1)} & x_1^{(2)} \\ x_2^{(1)} & x_2^{(2)} \end{pmatrix} \begin{pmatrix} 5.372 & 0 \\ 0 & -0.372 \end{pmatrix}$$

which expands to

$$\begin{pmatrix} x_1^{(1)} + 2x_2^{(1)} & x_1^{(2)} + 2x_2^{(2)} \\ 3x_1^{(1)} + 4x_2^{(1)} & 3x_1^{(2)} + 4x_2^{(2)} \end{pmatrix} = \begin{pmatrix} 5.372x_1^{(1)} & -0.372x_1^{(2)} \\ 5.372x_2^{(1)} & -0.372x_2^{(2)} \end{pmatrix}$$

This is a compact way of writing the four equations

$$\begin{aligned} x_1^{(1)} + 2x_2^{(1)} &= 5.372 x_1^{(1)} & x_1^{(2)} + 2x_2^{(2)} &= -0.372 x_1^{(2)} \\ 3x_1^{(1)} + 4x_2^{(1)} &= 5.372 x_2^{(1)} & 3x_1^{(2)} + 4x_2^{(2)} &= -0.372 x_2^{(2)} \end{aligned}$$

corresponding to the two original simultaneous equations and their two roots.

Finally, form X^{-1} from X and multiply eqn 25.5 by it from the left:

 $X^{-1}MX = X^{-1}X\Lambda = \Lambda$ (25.6)

A structure of the form $X^{-1}MX$ is called a similarity transformation. In this case the similarity transformation $X^{-1}MX$ makes M diagonal (because Λ is diagonal). It follows that if the matrix X that causes $X^{-1}MX$ to be diagonal is known, then the problem is solved: the diagonal matrix so produced has the eigenvalues as its only nonzero elements, and the matrix X used to bring about the transformation has the corresponding eigenvectors as its columns. In practice, the eigenvalues and eigenvectors are obtained by using mathematical software.

Brief illustration 25.3: Similarity transformations

To apply the similarity transformation to the matrix $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$

from *Brief illustration* 25.1 it is best to use mathematical software to find the form of X and X^{-1} . The result is

$$\boldsymbol{X} = \begin{pmatrix} 0.416 & 0.825 \\ 0.909 & -0.566 \end{pmatrix} \quad \boldsymbol{X}^{-1} = \begin{pmatrix} 0.574 & 0.837 \\ 0.922 & -0.422 \end{pmatrix}$$

This result can be verified by carrying out the multiplication

$$\boldsymbol{X}^{-1}\boldsymbol{M}\boldsymbol{X} = \begin{pmatrix} 0.574 & 0.837 \\ 0.922 & -0.422 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} 0.416 & 0.825 \\ 0.909 & -0.566 \end{pmatrix}$$
$$= \begin{pmatrix} 5.372 & 0 \\ 0 & -0.372 \end{pmatrix}$$

The result is indeed the diagonal matrix Λ calculated in *Brief illustration* 25.2. It follows that the eigenvectors $\mathbf{x}^{(1)}$ and $\mathbf{x}^{(2)}$ are

$$\mathbf{x}^{(1)} = \begin{pmatrix} 0.416\\ 0.909 \end{pmatrix} \mathbf{x}^{(2)} = \begin{pmatrix} 0.825\\ -0.566 \end{pmatrix}$$